The development of bioresorbable composite polymeric implants with high mechanical strength

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Implants for the treatment of tissue defects should mimic the mechanical properties of the native tissue of interest and should be resorbable as well as biocompatible. In this work, we developed a scaffold from variants of poly(glycolic) acid which were braided and coated with an elastomer of poly(glycolide-co-caprolactone) and crosslinked. The coating of the scaffold with the elastomer led to higher mechanical strength in terms of compression, expansion and elasticity compared to braids without the elastomer coating. These composite scaffolds were found to have expansion properties similar to metallic stents, utilizing materials which are typically much weaker than metal. We optimized the mechanical properties of the implant by tuning the elastomer branching structure, crosslink density, and molecular weight. The scaffolds were shown to be highly resorbable following implantation in a porcine femoral artery. Biocompatibility was studied *in vivo* in an ovine model by implanting the scaffolds into femoral arteries. The scaffolds were able to support an expanded open lumen over 12 months *in vivo* and also fully resorbed by 18 months in the ovine model.

Any soft tissues in the body undergo significant motion or experience substantial pressure. Strong, elastic, bioresorbable implants could be useful in cartilage repair, vascular grafts, sinusitis treatment, and the treatment of paediatric conditions. A major limitation of medical implants used to treat these tissues is the lack of materials that mimic the strength and elasticity of the native tissue. Beyond the mechanical properties, an ideal medical implant would also be resorbable, to provide utility only until the native tissue has healed.

To illustrate the capability of our scaffold, we focused on arterial disease, where strong, bioresorbable materials have been touted as the wave of the future¹⁻⁴. Here, bioresorbable scaffolds provide temporary strength-holding a vessel at an expanded diameter and resisting vessel recoil only until healing has occurredwhile eliminating a permanent foreign body. Balloon expandable, polymeric, bioresorbable scaffolds are fabricated from monolithic, highly crystalline, oriented, extruded tubes of polymers to achieve the necessary mechanical properties^{1,4,5}. Although such scaffolds have found applications in coronary arteries, these devices would fail in patients with peripheral arterial disease, whereby the vessels (such as the superficial femoral artery) undergo significant motion resulting in kinking and fracturing of the stiff devices. As a result, vessels with significant motion are currently treated using selfexpanding metal devices, which have the required strength to resist vessel recoil and are designed with elasticity and flexibility to withstand the forces resulting from vessel motion. Despite this, selfexpanding metal devices have high fracture rates associated with stent restenosis leading to significantly decreased vessel patency⁶.

An ideal stent in vessels experiencing significant motion would couple the benefits of self-expanding metal devices (strength and elasticity of native tissue) with those of bioresorbable devices (no permanent foreign body). Currently, no such device exists. The key challenge in creating any self-expanding implant is the need for the implant to be strong, elastic, and biocompatible. Designing a self-expanding device that is also bioresorbable is particularly challenging due to the limited strength of available materials. For example, 'strong' bioresorbable polymers have tensile properties that are only one-tenth those of the metals used in existing selfexpanding devices. This design challenge is further complicated by the environment of the vasculature, where materials have elicited higher inflammatory responses relative to other body locations⁷⁻¹¹. A final design complexity is that commonly used bioresorbable polymers are prone to stress relaxation. That is, when the device is crimped into a catheter for delivery to the target vessel, the strain on the device can lead to permanent deformation.

We hypothesized that we could create a self-expanding, bioresorbable implant utilizing a unique composite design. This design would consist of fibre braid (strong, highly oriented fibres in a design that enables bending) coated with an elastomer. The thermoset elastomer would be cured on the braid at the fully expanded diameter to provide a mechanism for the implant to 'spring back' or self-expand to its fabricated diameter by constraining the points of intersection of the braid. Utilizing this composite design, we have created an implant with radial force properties equivalent to metal using 'weak' polymeric materials that fully resorb.

Establishing design requirements

Our initial design efforts for a bioresorbable polymer implant focused on braiding fibres from commercially available 'strong' materials, such as poly(glycolide) (PGA) and poly(L-lactide) (L-PLA). These fibres were extruded and annealed to maximize the crystallinity and polymer orientation, in order to maximize the modulus of the materials. Despite these processing efforts, the PGA, L-PLA, and their copolymer poly(L-lactide-co-glycolide) (L-PLGA) fibres had significantly less mechanical stiffness than the stainless steel or nickel titanium (NiTi) materials that are used

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Figure 1 | Mechanical properties of the bioresorbable, self-expanding implant. a, Comparison of the modulus of materials used in the development of self-expanding stents. b, Comparison of mechanical properties of the Wallstent (stainless steel), S.M.A.R.T. (Nitinol), and elastomer-coated braid (L-PLGA coated with PGCL). A two-sided Student's *t*-test was used to determine significant differences in radial stiffness between the elastomer-coated implant and each of the other test articles.

to manufacture two benchmark self-expanding metal stent devices (Fig. 1a)¹². The Wallstent (Boston Scientific Corporation) utilizes stainless steel wires in a braided design, imparting flexibility and elasticity on this stiff, inelastic material (for example, 316L stainless steel has a tensile modulus = 200 GPa, elongation-to-break < 1%) while S.M.A.R.T. (Cordis Corporation) stent is fabricated from super-elastic metals, such as nickel titanium (NiTi), that possesses both stiff and elastic material properties (for example, NiTi used in S.M.A.R.T. stent has a tensile modulus = 40-75 GPa, elongationto-break = 10-15%). These differing approaches have resulted in stent designs with a range of mechanical properties. The radial stiffness (RRF), a measure of the stent's ability to withstand compression from a vessel, for the S.M.A.R.T. and Wallstent stents are 411 and 140 mmHg, respectively; the chronic outward force (COF), a measure of a stent's ability to expand the vessel wall, for the S.M.A.R.T. and Wallstent stents are 208 mmHg and 68 mmHg, respectively (Fig. 1b). These metal devices also recover fully to their initial diameter after deployment, as there is no stress relaxation leading to plastic deformation.

Base braid designs fabricated from optimally processed PLGA fibres had insufficient mechanical properties when compared to the above benchmark devices, consistent with the observations of others (Fig. 1b)¹³. In addition to the weak mechanical properties, stress relaxation was also observed when performing simulated deployments of the base braid. That is, the process of crimping the base braid to a 7 French (Fr) catheter to enable delivery to the target vessel and then expanding the device 10 min later led to significant stress relaxation of the polymers and permanent deformation of the device—resulting in a 25% reduction in the diameter of the braid, consistent with the results of others^{14,15}. We hypothesized that a successful bioresorbable, self-expanding implant should have mechanical properties similar to these benchmark metal devices.

Design and optimization of the elastomer

To impart desired mechanical properties to the base braid, we developed a bioresorbable elastomer material that would be used to coat the base braid. We hypothesized that the combination of the fibres comprising the base braid, coupled with an overlying elastomer coating that constrains the intersection points of the braid (Fig. 2a-c) would result in an implant with the ability to self-expand into a flexible, elastic structure with high radial

stiffness (Fig. 2d,e). Sufficient elasticity of the coating would be required to withstand the range of diameters experienced during the crimping and deployment process (for example, manufactured diameter \sim 7 mm \rightarrow diameter in catheter \sim 1.9 mm \rightarrow expanded diameter in vessel \sim 6 mm).

We developed the elastomer leveraging well-characterized, biocompatible materials from the PLA, PGA, and polycaprolactone (PCL) families. These materials degrade via hydrolysis into metabolites that can be safely eliminated from the body¹⁶. Because of this safe route of elimination, these materials have been widely used in the body as sutures, orthopaedic tissue fixation devices, and drug delivery systems¹⁷. Additionally, this class of polymers provides the ability to modulate the mechanical properties and absorption profile by combining the monomers at various compositions¹⁸.

The glass transition temperature (T_g) of an elastomer is critical in determining its elasticity. To ensure that the elastomer is not in the glassy state during crimping or deployment, its T_g must be less than room and body temperature. This requirement necessitated incorporation of ε -caprolactone into the elastomer, due to the low T_g of its polymers (-60 °C); in contrast, the T_g of lactide and glycolide polymers is above body temperature. However, homopolymers of ε -caprolactone are highly crystalline and prone to permanent deformation. Therefore, in addition to ε -caprolactone, we also selected glycolide and lactide as the building blocks of our initial elastomer to provide a fast resorbing, highly elastic material.

Initial elastomers were synthesized as linear prepolymers of poly(glycolide-co-caprolactone) (PGCL). We prepared films from this prepolymer and characterized their mechanical properties. This elastomer demonstrated a high elongation-to-break, although it was prone to high plastic deformation. As a result, when the stretched elastomer was released it would not recover to its original dimensions. We hypothesized this deformation was due to irreversible alignment of polymer chains under tensile forces. To decrease this deformation, we incorporated a four-arm branched initiator, pentaerythritol, into the reaction to create a four-arm branched prepolymer of PGCL (Fig. 2f). The four-arm structure provided 'crosslink' points in the prepolymer, helping to overcome plastic deformation and providing mechanical strength to the elastomer. Elasticity and deformation of the elastomer were further optimized by controlling the crosslink density of the elastomer. A tightly crosslinked elastomer, while strong, yielded a low elongation-to-break. In contrast, a loosely crosslinked system behaved similarly to the non-crosslinked



Figure 2 | **Creation of the strong, elastic, resorbable, self-expanding implant. a**, Scanning electron micrograph (SEM) of a bioresorbable PLGA base braid. **b**, SEM of base braid after the elastomer coating has been applied. This elastomer provides a mechanism for the fibres to return to nominal diameter, imparting strength on the device. **c**, False-coloured SEM of a cross-section of the intersection point of the elastomer-coated braid. The yellow areas represent the base braid and the blue area is the elastomer coating. **d**, Photograph illustrating self-expansion of the implant as it is deployed from a 7 Fr catheter. **e**, Photograph of the implant demonstrating flexibility of the design. **f**, Chemical reaction of the four-arm PGCL prepolymer and HDI to create the bioresorbable elastomer.

linear polymer; it had high elongation-to-break but was prone to plastic deformation. Figure 3a illustrates the mechanical properties of two, four-arm PGCL crosslinked elastomers prepared: one with low elongation-to-break and one with high elongation-to-break. The molecular weights of the prepolymers for these elastomers were 20,000 and 40,000 g mol⁻¹, respectively, and both elastomers were fabricated at a prepolymer-to-hexamethylene diisocyanate (HDI) ratio of 8:1 (wt/wt). Figure 3b,c shows the morphology of base braids coated with these elastomers after they have been crimped and deployed from a 7 Fr catheter. The low elongation-to-break elastomer-coated implant resulted in visible cracking of the material while the high elongation-to-break elastomer-coated implant had no cracking.

Crosslink density was controlled by adjusting both the molecular weight of the prepolymer and the amount of crosslinker used to prepare the elastomer. We created a series of elastomers using PGCL of different molecular weights (for example, 20,000 and $100,000 \,\mathrm{g \, mol^{-1}}$) with various amounts of HDI crosslinker (for example, ratio of elastomer to HDI of 20:1 to 20:4 by weight). Mechanical measurements demonstrated that higher molecular weight prepolymers with optimized crosslink density yielded elastomers with high elongation-to-break of 300% or greater (Supplementary Table 1).

Elastomers were further characterized to understand the contribution of plastic deformation to the material elongation. We hypothesized that an elastomer with high plastic deformation would lead to irreversible stretching during crimping, resulting in incomplete recovery of the elastomer-coated implant. We measured plastic deformation using cyclic mechanical loading. In this process, tensile testing was performed on dogbone-shaped samples for five consecutive cycles up to 300% strain, and the permanent deformation was defined as the residual strain at the beginning of the fifth cycle. Crosslink density and molecular weight were optimized to ensure less than 25% permanent deformation.

In summary, we created fully resorbable elastomers, leveraging well-characterized, biocompatible building blocks. We were able to 'lock' the intersection points of fibres on a base braid, by coating the braid with a thermoset elastomer. The coating was intended to restrain, but not restrict, pivoting of the fibre struts (if the coating is too restrictive, then the fibre struts would bend, potentially leading to buckling, deformation, or poor recovery). To optimize mechanical properties, we incorporated polymer branching along with modulation of crosslink density and molecular weight. We selected an optimized, branched PGCL elastomer with greater than 300% elongation-to-break and less than 25% permanent



Figure 3 | Mechanical properties and morphology of low- and high-elongation material. a, Representative stress-strain curves of films for two PGCL elastomers: onewith high and one with low elongation-to-break. **b**, Scanning electron micrograph depicting cracked morphology of a low elongation-to-break elastomer applied to a base braid, and subsequently crimped and deployed. **c**, Scanning electron micrograph depicting non-cracked morphology of a high elongation-to-break elastomer applied to a base braid, and subsequently crimped and deployed.

deformation for further study. Doing so yielded a strong implant from 'weak' materials.

Our composite structure created an implant with unique properties relative to current polymeric resorbable stents that utilize monolithic, highly crystalline, oriented, extruded polymer tubes. These devices include Remedy (Kyoto Medical), Bioresorbable Vascular System (Abbott), and Desolve (Elixir) stents. Although the latter two devices have good radial strength, they have minimal COF and therefore are not self-expanding. This data highlights the uniqueness of the design created herein.

Acute mechanical properties

The optimized PGCL elastomer was applied to the base braid and cured, creating a polyester with urethane crosslinks (polyester/polyurethane) as shown in Fig. 2f. The resulting implant had a strut diameter and angle of approximately 125-175 µm and $120-130^{\circ}$, respectively, with a cell size between $0.024-0.030 \text{ mm}^2$. An implant comprised of 10:90 L-PLGA fibres coated with PGCL (10:90/PGCL) elastomer resulted in a device with strong mechanical properties, exhibiting an RRF = 712 ± 45 mmHg and $COF = 151 \pm 5$ mmHg. In contrast, the same braid without an elastomer coating had mechanical properties of RRF = $90 \pm 5 \text{ mmHg}$ and $COF = 28 \pm 3 \text{ mmHg}$ (Fig. 1b). These results demonstrate that the elastomer coating substantially improved the mechanical properties of the base braid, achieving mechanical properties similar to benchmark self-expanding metallic stents while utilizing fully resorbable materials (Fig. 1b). Radial force testing under multiple cycles indicated that the maximum acute plastic deformation response decreased the RRF by \sim 25% while the COF remains essentially unchanged (at 4.5 mm diameter). Over a range of target vessel diameters, the RRF is relatively constant, with values between 890 \pm 54 to 823 \pm 61 mmHg, while the COF ranges from 243 ± 9 to 118 ± 7 mmHg (Supplementary Fig. 1). These results are particularly remarkable when considering that the mechanical properties of the starting materials for the bioresorbable were considerably weaker than those used in metal stents. Application of the optimized elastomeric coating had an additional benefit—an acute recovery greater than 95% of the manufactured diameter was demonstrated, overcoming the acute stress relaxation of the base braid during crimping and deployment. To avoid the long-term

effects of prolonged duration in a crimped state on the ability of an implant to self-expand, our implants will be packaged in an uncrimped state along with a delivery system that contains a mechanism to crimp the implant into a catheter immediately prior to its use.

Chronic properties and vascular biocompatibility

Beyond the acute phase, a critical characteristic of any selfexpanding, resorbable implant is the biocompatibility throughout its resorption. The materials resorb via a hydrolytic resorption mechanism through random scission of the ester linkage in the polymer's backbone, as shown in Supplementary Fig. 2. The major resorption products from this hydrolytic process are the small molecules lactic acid, glycolic acid, and 6-hydroxyhexanoic acid from the PLA, PGA and PCL polymer segments, respectively^{19,20}. These small molecules or further degradants of these small molecules then enter the tricarboxylic acid cycle and are eventually eliminated from the body as carbon dioxide and water. The urethane/urea segments make up less than 4% by weight of the implant and degrade via an oxidative mechanism, giving rise to the small molecule hexamethylenediamine (HDA)²¹. HDA is then eliminated from the body via urine^{22,23}.

To assess the biocompatibility of the 10:90/PGCL design, devices fabricated with 6 mm diameter were implanted in ilio-femoral arteries in swine. Placement was successful for all devices in the target 4-5 mm vessel diameter as measured by angiography, confirming the acute mechanical performance of the device in vivo. Animals were euthanized at 30 or 90 days, based on the expected resorption time of the 10:90/PGCL device of 3-4 months. At both follow up time points, no evidence of implant migration, thrombosis, dissection, or aneurysm was observed. All vessels were open and patent by angiography (defined as less than 50% binary stenosis), although some level of stenosis at 30 days was noted (Fig. 4a-d). Although angiographic results were promising, histologic analysis demonstrated a significant inflammatory response and the presence of granuloma at 30 days (Fig. 4e,f and Supplementary Table 2). Disruptions of the IEL and EEL were frequent and associated with inflammation, indicating substantial vessel injury. A significant neointimal response was also observed at 30 days, with some resolution by 90 days. Moderate resorption was observed

NATURE MATERIALS DOI: 10.1038/NMAT5016



Figure 4 | **Testing of 10:90/PGCL implant** *in vivo* in swine ilio-femoral vessels. **a**-**d**, Angiography images depicting vessel patency at 30 and 90 days. Panels **a**,**c** show the raw angiography of the vessel, while panels **b**,**d**, show the angiogram that has been quantitatively analyzed for stenosis. **e**,**f**, Histology images stained with haematoxylin and eosin demonstrating a severe inflammatory response at 30 days (**e**), with some resolution by 90 days (**f**).

by histology at 30 days, and substantial resorption was seen at 90 days. The inflammatory response and the associated granuloma were attributed to the fast resorption of the implant. Overall, the biocompatibility of this implant was deemed unacceptable.

To study the impact of slowing the resorption of the device on vascular compatibility, two additional designs were evaluated: a 75:25 L-PLGA base braid coated with the same PGCL elastomer (75:25/PGCL) and a 75:25 L-PLGA base braid coated with a PLCL elastomer (75:25/PLCL). Doing so enabled us to study the impact of slowing the resorption of the base braid only (that is, comparison of 10:90/PGCL with 75:25/PGCL) versus slowing the resorption of the elastomer (that is, comparison of the 75:25/PGCL with 75:25/PLCL). Both of these strategies utilized the slower resorption of L-lactide as compared to glycolide¹². Resorption times of these base braids and implants were compared using an in vitro accelerated resorption assay. In this assay, one day of accelerated resorption corresponded to approximately one week of real-time resorption. Comparison of the resorption time of the two base braids (75:25 and 10:90) and the three coated devices (10:90/PGCL, 75:25/PGCL, 75:25/PLCL) demonstrated that the 10:90 devices resorbed more quickly than the 75:25 devices (Fig. 5), as expected based on the higher glycolide concentration¹². The elastomer coating on the 10:90/PGCL implant slowed its resorption relative to the 10:90 base braid. Similarly, the PLCL coating on the 75:25/PLCL device decreased the resorption relative to the 75:25 base braid. In contrast, the 75:25/PGCL device had similar resorption to the uncoated base braid. These results indicate that the resorption time of the 75:25 and the PGCL elastomer were likely similar, leading to no change in overall resorption time with the coating. On the basis of these results, and the correlation between accelerated and real-time resorption, the 10:90/PGCL should resorb in vitro in approximately 4 months-consistent with our *in vivo* results. Extrapolating from in vitro results, the anticipated resorption times for the 75:25/PGCL and the 75:25/PLCL were 6-7 months and 9-10 months, respectively.

When implanted in swine, all vessels with the 75:25/PGCL and 75:25/PLCL devices remained patent by angiography at 30, 90,



Figure 5 | Accelerated *in vitro* resorption time of base braids and elastomer-coated implants. Comparison of residual mass of 10:90 L-PLGA, 75:25 L-PLGA, and 85:15 L-PLGA base braids with their corresponding elastomer-coated devices (10:90/PGCL, 75:25/PGCL, 75:25/PLCL, and 85:15/PLCL). Each day represents approximately 1 week in real-time resorption. Each data point represents the mean and standard deviation on n = 3 to 5 samples.

and 180 days. Additionally, all vessels were fully endothelialized by 30 days. In the 75:25/PGCL group, significant *in vivo* resorption had occurred at 90 days (consistent with *in vitro* predictions), as evidenced histologically by the decreasing size of implant struts and penetration of cells into the device remnants over time. This resorption coincided with a strong inflammatory response with the presence of granuloma. By 180 days, this inflammatory response had partially subsided, but we deemed the device incompatible based on the 90-day response. Examination of the slowest degrading 75:25/PLCL device revealed excellent histological compatibility (Fig. 6a). Only a minimal-mild inflammation was observed at 30 and 90 days; disruptions of the IEL and the EEL were rare. The overall stenosis observed in this device was



Figure 6 | **Histological results of elastomer-coated implants through full resorption. a**, Haematoxylin and eosin stained images of 75:25/PLCL implants *in vivo* in swine ilio-femoral vessels. (i-iv) Low-magnification histology images depicting vessel patency and time course of resorption. Scale bar represents 1 mm. (v-viii) High-magnification histology images showing time course of inflammatory response and resorption of individual struts. Scale bar represents 50 µm. **b**, Haematoxylin and eosin stained images of 85:15/PLCL implants in sheep superficial femoral or profunda arteries. (i-iv) Low-magnification images depicting vessel patency and resorption over time. Scale bar represents 1 mm. (v-viii) High-magnification images showing time course of inflammatory response and resorption of individual struts. Scale bar represents 1 mm. (v-viii) High-magnification images showing time course of inflammatory response and resorption of individual struts. Scale bar represents 100 µm. For all images, the asterisks indicate implant struts; white arrows show remnants of polymer material; black arrows point to neointimal tissue; Lu indicates the lumen.

mild and considered to be acceptable (average diameter stenosis measured by angiography of $9.1 \pm 2.7\%$ and $7.4 \pm 5.6\%$ at 90 and 180 days, respectively). Minimal resorption was observed at 90 days, although occasional cell infiltration was observed histologically in the implant struts, indicating resorption had initiated. Significant resorption occurred at 180 days, with only small remnant particles of the device remaining. In contrast to the PGCL devices, this resorption was accompanied by a modest amount of inflammation and minimal IEL/EEL disruption. These results suggest excellent compatibility of the 75:25/PLCL bioresorbable implant throughout the resorption process. Detailed quantitative assessments of the implantation and semi-quantitative comparison of injury, inflammation, and fibrin between groups and time points are provided in Supplementary Table 2.

Overall, the three implant designs tested demonstrated distinct resorption profiles. These results indicate the importance of the resorption properties of the device, both the base braid and the elastomer, on its vascular compatibility. These results are consistent with others who have demonstrated the importance of controlling the rate of implant resorption within the initial critical vessel healing period²⁴.

Addressing elastic recoil

It has been previously hypothesized that a bioabsorbable stent should not lose mechanical properties until the vessel has fully remodelled to avoid chronic recoil (estimated time \sim 90 days).

Although the 75:25/PLCL device demonstrated excellent compatibility in animals, bench data indicated that this device exhibited minimal COF after 28 days (Supplementary Fig. 3). In an effort to extend the retention of mechanical properties, an additional variant of the implant was studied that used 85:15 L-PLGA fibre as the base braid material with a PLCL elastomer coating, 85:15/PLCL, and were able to demonstrate measurable properties out to 3 months (Supplementary Fig. 3). Fatigue testing on this design showed mechanical integrity out to 22 weeks (Supplementary Fig. 4).

We conducted an additional preclinical study to examine the biocompatibility of the 75:25/PLCL and 85:15/PLCL devices throughout their full resorption. In this study, we utilized the femoral and profunda vessels in an ovine model to assess compatibility in a second species and vessel bed. The ovine model was selected because it provides longer and larger vessels in the legs, representing a closer anatomy to human superficial femoral arteries²⁵. In addition, the ovine model has a coagulation and fibrinolytic system with more similarities to that of humans than other species²⁵. In this model, the majority of the base braid in the 75:25/PLCL device was absorbed by 6 months, similar to the findings from the swine model. As expected, the 85:15/PLCL base braid demonstrated a longer resorption time compared to the 75:25/PLCL, with full resorption by 18 months. In both designs, a mild to moderate amount of inflammation without granuloma was present, minimal vessel injury was observed, and the EEL was fully intact at all time points, again indicating acceptable vascular

compatibility from implantation through to resorption (Fig. 6b and Supplementary Table 3). The 85:15/PLCL optimized implant design is biocompatible and addresses elastic recoil of the blood vessel by maintaining mechanical properties for 3 months.

In summary, we have developed a unique composite design to create a bioresorbable, self-expanding implant consisting of an elastomer coating that can be applied to a base braid to provide mechanical strength and to resist stress relaxation. Leveraging this composite design we have created an implant with acute properties similar to metal benchmark devices from 'weak' polymer materials. The self-expansion and mechanical properties allow the implant to be delivered into and conform to various cavities within the body.

This composite device, which is bioresorbable and selfexpanding, meets all the design requirements for vessels undergoing significant motion: it is strong, elastic, and biocompatible. Given that preclinical safety of the device has been established, the next step is to examine the device in human clinical studies. In particular, the chronic recoil performance of the implant in calcified lesions could be a limitation and needs to be evaluated. This device has the potential to be the first bioresorbable, fully self-expanding implant, affording patients an alternative treatment option.

The applicability of the composite strategy described herein goes beyond the specific bioresorbable device described herein. Bioresorbable implants eliminate any permanent nidi for chronic irritation. The coupling of strong materials with elastomeric materials provides an approach to create bioresorbable constructs that mimic the properties of native soft tissue. This approach has tremendous potential in the development of new implants to treat diseases of soft tissue across the body.

Methods

Methods, including statements of data availability and any associated accession codes and references, are available in the online version of this paper.

Received 13 August 2015; accepted 25 September 2016; published online 20 November 2017

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Acknowledgements

We thank J. Anderson, R. Virmani, R. Schwartz, and S. Hilbert for consultation and feedback. We acknowledge the efforts of A. Pappas, T. Ng, K. Ho, I. Gitlin, P. Zamiri, W. Naimark, A. Rago, D. Sundaresh, J. Marini, S. Morneau, M. Le, S. Varughese and K. Un in device fabrication, data collection, analytical evaluation, and manuscript review.

Author contributions

U.S., D.C., L.C., Y.K., C.Y., G.Z., R.B., S.W. and M.P. conceived the experiments. C.Y. and J.M. performed the experiments. U.S., D.C., L.C., Y.K., C.Y., Q.P., G.Z. R.B. and S.W. undertook analysis of the data and results. U.S., D.C., L.C., Y.K., C.Y, Q.P., R.L. and G.M.W. wrote the manuscript.

Additional information

Supplementary information is available in the online version of the paper. Reprints and permissions information is available online at www.nature.com/reprints. Correspondence and requests for materials should be addressed to M.P.

Competing financial interests

Upma Sharma PhD, Danny Concagh MS, Lee Core MSE, Yina Kuang PhD, Changcheng You PhD, Quynh Pham PhD, Greg Zugates PhD, Rany Busold BS, Jonathan Merlo BS, Stephanie Webber BS and Maria Palasis PhD were employees of 480 Biomedical at the time of this work. All authors have stock options in 480 Biomedical.

NATURE MATERIALS DOI: 10.1038/NMAT5016

Methods

Synthesis and characterization of the elastomer. To synthesize the elastomer prepolymer, a catalyst Sn (Oct)₂, initiator pentaerythritol, and the monomers were added to a round-bottom flask at the desired ratio (for example, for the poly(glycolide-co-caprolactone) (PGCL) prepolymer, the flask was charged successively with Sn(Oct)₂ (10.5 mg), pentaerythritol (300 mg), glycolide (30.0 g), and ε -caprolactone (30.0 g)). The reaction proceeded at 170 °C under a nitrogen atmosphere for 24 h. The resulting prepolymer was precipitated, washed thoroughly and dried. A ¹H NMR in CDCl₃ was acquired to measure the lactide:caprolactone mol:mol polymer composition, and a gel permeation chromatograph (GPC) using poly(methyl methacrylate) as standards was acquired to measure the M_n , M_w , and the polydispersity index (PDI).

Films of the PGCL elastomer were prepared by dissolving the PGCL prepolymer (1.0 g) with hexamethylene diisocyanate at various concentrations in 20 ml of dichloromethane (DCM). The solution was poured into a 10 cm aluminium pan, dried, and cured at 100 °C for 16 h. The elastomer films were cut into dog bone-shaped coupons 3.18 mm in width for Instron testing. The coupons were loaded onto the grips with a separation of 15 mm and the stress-strain responses of the films were measured at room temperature.

Fabrication of the devices. Fabrication of the implants required several steps: braiding of the base braid; spray coating the elastomer prepolymer onto the base braid; and curing the elastomer. To fabricate the base braid, poly(L-lactide-co-glycolide) (L-PLGA) resins purchased from Corbion were first melt-extruded into fibres at Biogeneral. These fibres were spooled onto 32 individual bobbins and then braided along a mandrel. Braids were annealed on the mandrels under tension (30 min at 95 or 120 °C for 75:25 and 10:90, respectively, and 22 h at 130 °C for 85:15) and then stored frozen until use. At the time of use, braids were removed from the mandrel, cut to the desired length, and radiopaque marker bands (platinum/tungsten) were manually placed on the ends of the device.

For spray coating, the braid was mounted onto a specially designed holding fixture that enabled complete coating of the braid fibres. The elastomer prepolymer and crosslinker (hexamethylene diisocyanate, HDI) were dissolved in dichloromethane (for example, 10 g of PGCL prepolymer and 1.87 ml of HDI in 200 ml of solvent). This solution was spray coated to achieve a conformal coating of the braid. The braid was rotated and horizontally translated throughout the spraying process to ensure a uniform coating along the length of the device. The mass of the elastomer was optimized to achieve the desired mechanical properties (Supplementary Fig. 5). After spray coating of the elastomer, the holding fixture with the coated braid was placed in an oven and heated at elevated temperatures (100 °C was used for the 10:90, 75 °C for the 75:25, and a staged heating system of 75 °C and then 100 °C for the 85:15).

Measurement of the properties of the self-expanding, bioresorbable device. To characterize the self-expanding, bioresorbable device, we measured the acute radial stiffness and the diameter after simulated deployment. The RRF and COF were quantified using a Radial Force Gauge (Machine Solutions, Flagstaff, AZ). Test articles were placed into a cylindrical 'iris' fixture which compressed the implant to a 7 Fr diameter, then increased in diameter to allow the implant to expand. Measurements were taken at nominal implant diameter minus 1.5 mm (that is, target vessel diameter) during the compressive and expansive parts of the cycle; RRF as the diameter decreased, and COF as the diameter increased. Testing on benchmark devices was performed on n = 2 or 3 samples, while testing on elastomer-coated braids was performed on a minimum of n = 3 samples. Dimensional scaling of the radial forces of our implant at 6 mm nominal diameter to the 7 mm nominal diameter of the benchmark devices was performed. A Student's t-test was used to determine significant differences in radial stiffness between the elastomer-coated implant and each of the other test articles. Samples for characterization of retention of mechanical properties (n = 5) were placed in phosphate-buffered saline (PBS) and, at designated time points, were removed, dried, and subsequently tested as described above.

Implant diameter was measured after simulated deployment using a laser micrometer as a measurement of recovery. Test samples were loaded into 7 Fr delivery catheters, flushed with (PBS) for 10 min, then placed in a 37 °C PBS bath for 10 min, simulating delivery in the body. After simulated loading and delivery, test samples were deployed into a 37 °C bath, removed from the bath, and dried. Within one minute of deployment, implant outer diameter was measured using a laser micrometer in six locations.

Fatigue testing was performed on 85:15/PLCL designs to evaluate cyclic loading on implant integrity. Implants were deployed into 5.5 mm diameter compliant silicone tubing and then subjected to cyclic bending by a 1.5 inch radius drum at a frequency of 1 Hz. Visual observations were made on a weekly basis for signs of fracture or failure. Additionally, the in-vessel lengths of the implants were measured as a surrogate for implant failure. The relevance of this measurement is that, as a consequence of recoil, the implant diameter will decrease, resulting in an increase in its length (that is, the implant forelengthens as it becomes smaller in diameter). By monitoring length, sudden reductions can be detected, suggesting the implant mechanically fails in such a way that the vessel elastically springs back to its original length.

Description of accelerated resorption assay. Implants were placed unconstrained individually in glass vials filled with 20 ml of phosphate/citrate/borate buffer solution at a pH = 12.0. The vials were placed in a shaking water bath at 37 °C. At a designated time point, the implants were removed from the solution, rinsed with de-ionized water, and dried under vacuum until a constant weight was obtained. The % mass loss at that time point is calculated as outlined in the equation below. The mass loss experiments were terminated once the implants lost their integrity.

%Mass loss =	Initial scaffold mass - Scaffold mass at designated time point
	Initial implant mass
	× 100

Data demonstrated that one day under accelerated conditions (pH 12, 37 $^{\circ}$ C) was roughly equal to 8.5 days under physiological conditions (pH 7.4, 37 $^{\circ}$ C) (Supplementary Fig. 6).

Preclinical assessment. Two preclinical studies were conducted to assess the biocompatibility of various implant designs. The first study evaluated 10:90/PGCL, 75:25/PGCL, and 75:25/PLCL designs in healthy non-atherosclerotic Yucatan mini/hybrid farm swine, whereas the second study evaluated 75:25/PLCL and 85:15/PLCL designs in adult Suffolk Cross-bred sheep. Full characterization data of these implant designs can be found in Supplementary Table 4. All animal work was performed under the oversight of the Comité institutionnel de protection des animaux d'AccelLAB and was ensured compliant with the Canadian Council on Animal Care. Devices were fabricated to a nominal diameter of 6 or 7 mm and a length of 20 mm. Immediately prior to implantation, the implants were loaded into a 9.5 Fr catheter-based delivery system and were delivered to the target vessels. Vessel sizes were selected to ensure sufficient vessel bump-out (that is, to ensure the device did not interfere blood flow and to control vessel injury due to chronic outward force). Implant-to-artery ratio was targeted to between 1.15 and 1.25 for the swine study and between 1.00 and 1.15 for the sheep study. Animals were euthanized at desired time points between 1 and 18 months. There were at least n = 4 samples for each group tested at each time point. After euthanization, implants were harvested and preserved in formalin, dehvdrated, and embedded in paraffin. Three cross-sections (proximal, middle, and distal) for each implant were cut using a microtome, and stained for histopathological evaluation. The semi-quantitative scoring scheme for injury, inflammation, and fibrin are described in Supplementary Table 5. The preclinical proof-of-concept studies were conducted to efficiently utilize the number of available animals with the goal of providing directional information for iterating on implant design. Therefore, the studies were not appropriately powered to make statistical observations.

Data availability. The authors declare that all relevant data supporting the finding of this study are available within the paper and its Supplementary Information files. Additional data are available from the corresponding author upon request.